

Panel on Innovations in Traditional UUVs

Riptide

Presented by Jeffrey M. Smith

President & CEO

April 2016

Riptide Founders / Leads



Jeffrey M. Smith

President & CEO

BS - Mech Eng (WPI)

MS - Mech Eng (RPI)

MBA - (RPI)

20+ Years in technical management, program management, executive management, Navy Program Development, UUV Subject Matter Expert



Dr. Dani Goldberg

Software Principal

BS -Comp Sci (Brandeis)

MS - Comp Sci (USC)

PhD - Comp Sci (USC)

20+ Years in technical management and software development for autonomous systems (space and undersea), architecture development, hybrid systems



Dr. Stefano Brizzolara

Naval Architecture Principal / Founder

PhD – Numerical Hydrodynamics for

Ship Design (Univ of Genoa)

~20 Years in naval architecture for advanced surface craft, architecture development, hydrodynamic design

Lenny Baker

Sr. Lead Systems Engineer / EE / SW

BS - Elec Eng (WPI)

MS – Elec Eng (Umass)

10+ Years in electrical design, shipboard electronics, power and controls

Sam Godin

Lead Mechanical Engineer

BS - Mech Eng (WPI)

20+ Years in mechanical design, SolidWorks Super User

SCPO (ret) Dan Lawrence

Lead Analyst

Retired ONI ACINT Specialist, Operational Test Director, 30+ years experience in at-sea technical assessment for operational utility

Riptide Innovation

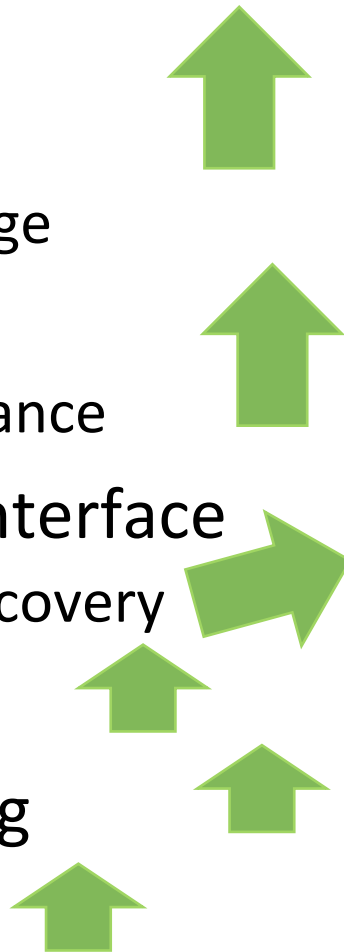


- Persistence - Efficiency coupled with energy capacity is a very big deal
 - Electrical Efficiency – Focused on low power processing
 - Hydrodynamic Efficiency – Focused on low drag
 - Capacity – Exclusively partnered with Open Water Power
 - Game Changing – Estimated 5 kWh on a micro-UUV
- Flexibility
 - Open HW and SW Interfaces
 - Extensive use of Open Source
 - High COTS Content
 - Rapid Manufacturing
 - Building a robust user community



UUV Technology Challenges

- Energy
 - Energy Density
 - Certification
 - Platform Storage
- Reliability
 - Mission Endurance
- Host Platform Interface
 - Launch and Recovery
- Autonomy
- Mission Planning
- Affordability



State of Practice in Unmanned Systems Technology

NDIA Unmanned Undersea Vehicle Study Team Report

July 2009



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